

NP completeness

Course "Discrete Biological Models" (Modelli Biologici Discreti)

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Laurea Triennale in Bioinformatica
a.a. 2014/15, fall term

NP-completeness and the real world

Imagine you are working for a biotech company. One day your boss calls you and tells you that they have invented a new sequencing technology. It generates lots of fragments of the target molecule, which may overlap. Your job as **chief algorithm designer** is to write a program that reconstructs the target molecule.

You get to work ...

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NP-completeness and the real world

Imagine you are working for a biotech company. One day your boss calls you and tells you that they have invented a new sequencing technology. It generates lots of fragments of the target molecule, which may overlap. Your job as **chief algorithm designer** is to write a program that reconstructs the target molecule.

You get to work ...
you find that ...

- you need a superstring (of all fragments)
- a shortest superstring
- you need to maximize the overlaps
- any superstring is just a permutation of the fragments
- you need the/a best permutation (which maximizes total overlap)

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NP-completeness and the real world (2)

But after weeks and weeks and weeks ...
all you have come up with is:

Exhaustive algorithm

List all possible permutations and choose the best.

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NP-completeness and the real world (3)

This is no good, since for 1,000 fragments (typical experiment) this would need far longer than the age of the universe. Why?

- $1000! \approx 4 \cdot 10^{2567}$ permutations source: Wolfram Alpha
- say we need 1000 operations per permutation (summing overlaps)
- if we have a computer that does 1 billion ($= 10^9$) operations/sec
- it can handle 1 million (10^6) permutations per second
- So it will take $4 \cdot 10^{2567} / 10^6 = 4 \cdot 10^{2561}$ seconds

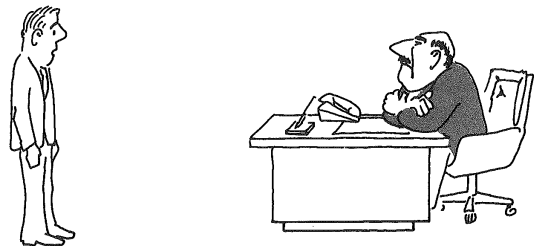
Age of the universe:

about 14 billion years $\approx 4 \cdot 10^{17}$ seconds

source: Wikipedia

We can see that a million (10^6) or a billion (10^9) times faster computer wouldn't help much, either. Nor would faster handling of the permutations.

So you can go to your boss and say:



"I can't find an efficient algorithm, I guess I'm just too dumb."

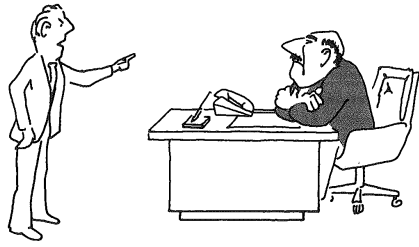
Bad idea, you may get fired!

source: Garey & Johnson, A Guide to the Theory of NP-completeness, 1979

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Or you could say:



"I can't find an efficient algorithm, because no such algorithm is possible!"

Unfortunately, it is very hard to do impossibility proofs. . .

source: Garey & Johnson, A Guide to the Theory of NP-completeness, 1979

You prove that the reconstruction problem is NP-complete, and you say:



"I can't find an efficient algorithm, but neither can all these famous people."

So it makes no sense to fire you and get another expert!

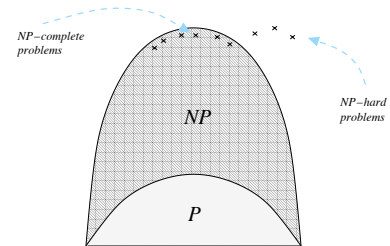
source: Garey & Johnson, A Guide to the Theory of NP-completeness, 1979

Overview

- **P** - class of problems that can be solved efficiently (i.e., in polynomial time)
- **NP** - class of problems that can be solved in polynomial time by a non-deterministic Turing machine ([nicer definition to follow](#))
- **NP-complete problems** - maximally difficult problems in NP: every other problem can be transformed into these in polynomial time ([details later](#))
- **NP-hard problems** - like NP-complete problems, but not necessarily in NP

Overview

Usual way of drawing the classes P and NP:



The class P

Definition

A decision problem X is in P if there is a polynomial time algorithm A which solves X .

A **decision** problem is one that allows only YES or NO answers.

Examples

- Given a sorted array of n numbers, is number x present? $O(\log n)$ time
- Given an array of n numbers, is number x present? $O(n)$ time
- Given a graph G , is G Eulerian? $O(n + m)$ time, where $n = |V|, m = |E(G)|$.
Details: Determine for each vertex whether it has even degree (or whether it is balanced if G is a digraph) in $O(n)$ time; determine with BFS whether G is connected in $O(n + m)$ time.

Polynomial time algorithms

Algorithm A is **polynomial time** if there is a polynomial p s.t. for every input I of size n , A terminates in at most $p(n)$ steps.

size is usually measured in bits, number of elements (for an integer array), number of vertices and edges (for graphs), number of characters (for strings)

The class NP

NP - class of problems that can solved in polynomial time by a non-deterministic Turing machine (non-deterministic polynomial time)

alternative definition:

NP = class of polynomial time checkable problems

Whenever the answer is YES, there must exist a certificate (proof) of this, and it must be checkable (verifiable) in polynomial time.

Example

Problem: Given a graph $G = (V, E)$, is G Hamiltonian (i.e. does it have a Hamiltonian cycle)?

Certificate: A Hamiltonian cycle: check whether it is a cycle, and whether it contains every vertex exactly once, in $O(n)$ time, where $n = |V|$.

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The class NP

NP = class of polynomial time checkable problems

Whenever the answer is YES, there must exist a certificate (proof) of this, and it must be checkable (verifiable) in polynomial time.

Example

Problem: Given a fragment set \mathcal{F} of m fragments, does a superstring of length $\leq k$ exist?

Certificate: a superstring S of length $\leq k$: check for every f whether f is substring of S , in $O(|f| + |S|)$ time; altogether $O(|\mathcal{F}| + m|S|)$ time, so polynomial in input size.

input: \mathcal{F} , inputsize: $|\mathcal{F}| = \sum_{i=1}^m |f_i|, |S| \leq \sum_i |f_i|$, so $m|S| \leq |\mathcal{F}|^2$

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The class NP

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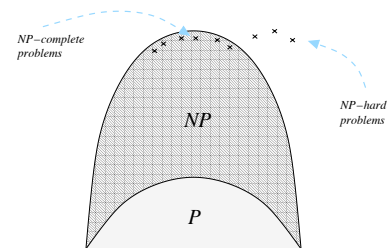
Example

Problem: Given a complete digraph $G = (V, E)$ with non-negative weights on edges, does it have a Hamiltonian path of weight at least r ?

Certificate: a Ham. path of weight $\geq r$: check weight of path, check whether it contains every vertex exactly once, in $O(n)$ time, where $n = |V|$

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P and NP



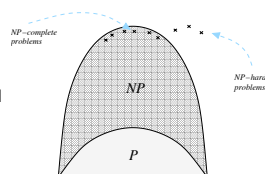
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The P = NP question

One of the big open question of computer science is:

Is $P = NP$?

- Since $P \subseteq NP$ is clear, the question is: $NP \subseteq P$?
- Can every problem in NP be solved efficiently?
- I.e. is the shaded area empty?



N.B.: There is a US \$ 1,000,000 prize for solving this question.

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The P = NP question

Most people believe: $P \neq NP$.

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NP-complete and NP-hard problems

NP-complete problems

A problem X is **NP-complete** if

- it is in NP
- every problem in NP can be transformed/reduced to it in polynomial time (**details soon**)

NP-hard problems

A problem X is **NP-hard** if

- every problem in NP can be transformed/reduced to it in polynomial time (**details soon**)

i.e., the only difference is that it is not necessarily itself in NP .

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NP-complete and NP-hard problems

Theorem

Let X be an NP -complete or NP -hard problem. If we find a polynomial time algorithm for X , then $P = NP$.

Corollary

Let X be an NP -complete or NP -hard problem. Then there is no polynomial time algorithm for X , unless $P = NP$.

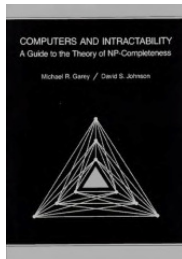
Since we all believe that $P \neq NP$, this means in practical terms:

In practice

Let X be an NP -complete or NP -hard problem. Then there is no polynomial time algorithm for X , **fullstop**.

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NP-complete problems



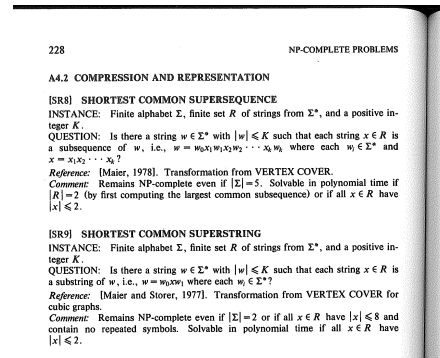
Michael R. Garey, David S. Johnson, *Computers and Intractability - A Guide to the Theory of NP-completeness*, 1979

one of the best known and most cited books ever in computer science

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NP-complete problems

Contains a list of known NP-complete problems:



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NP-complete problems

You have found your problem (the **Shortest Common Superstring** Problem) in the Garey-Johnson:



"I can't find an efficient algorithm, but neither can all these famous people."

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Decision problems vs. optimization problems

Optimization problem

Given \mathcal{F} , find a shortest common superstring S .

Decision problem

Given \mathcal{F} , does a common superstring S exist with $|S| \leq k$?

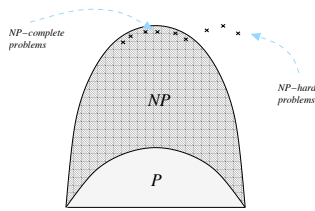
N.B.

If I can solve the decision problem, then I can also solve a reduced version of the optimization problem: determining the length of an SCS. Use $\log(|\mathcal{F}|)$ many calls to the decision problem.

(Details: Determine the length of an SCS using binary search: Let $N = |\mathcal{F}|$. We know that a common superstring exists with length N , namely the concatenation of all $f \in \mathcal{F}$. Now set $k = N/2$; if the answer is YES, continue with $k = N/4$, else with $k = 3N/4$, etc.)

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Decision problems vs. optimization problems



- Many *NP*-hard problems are optimization versions of *NP*-complete problems.
- If the decision version is *NP*-complete, then the optimization version is automatically *NP*-hard. (Why?)
- So it's enough to prove that the decision version is *NP*-complete. (Or to find it in the Garey-Johnson.)

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Polynomial time reductions/transformations

Now we want to talk about *NP*-complete problems. These are the ones to which all others in *NP* can be reduced in polynomial time. What does this mean?

“Translate problem *X* to problem *Y* in polynomial time”

Definition

We say that problem *X* is **polynomial time reducible** to problem *Y*, $X \leq_p Y$, if there is an algorithm *A* and a polynomial *p*, s.t. for every instance *I* of *X*, *A* constructs an instance *J* of *Y* **in time $p(|I|)$** such that:

I is a YES-instance of *X* $\Leftrightarrow J$ is a YES-instance of *Y*.

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An example reduction

SCS-decision

Given: Fragment set \mathcal{F}

Question:

Does a superstring of length $\leq k$ exist?

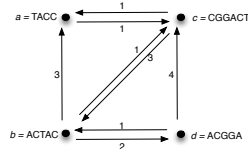
Example

{TACC, CGGACT, ACTAC, ACGGA}

Weighted Hamiltonian path-decision

Given: A weighted complete digraph *G*.

Question: Does *G* have a Ham. path of weight $\geq \|\mathcal{F}\| - k$?



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An example reduction

Let \mathcal{F} contain *m* fragments of length *r*.

- **Time for transformation:** $O(m^2 r^2)$, (or even faster): the time of the transformation is dominated by the time for computing the overlaps between the fragments, i.e. the weights on the edges
- This is **polynomial** in the input size $\|\mathcal{F}\| = mr$ (namely, with polynomial $p(n) = n^2$).
- YES on the left \Leftrightarrow YES on the right
- Therefore we have shown:
 $SCS\text{-}decision \leq_p \text{Weighted Hamiltonian path-decision}$

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Polynomial time reductions/transformations

Definition (again)

We say that problem *X* is **polynomial time reducible** to problem *Y*, $X \leq_p Y$, if there is an algorithm *A* and a polynomial *p*, s.t. for every instance *I* of *X*, *A* constructs an instance *J* of *Y* **in time $p(|I|)$** such that:

I is a YES-instance of *X* $\Leftrightarrow J$ is a YES-instance of *Y*.

N.B.

- Think of $X \leq_p Y$ as meaning: *X* is “not harder” than *Y*
- Note that we are still paying for the reduction/transformation: it takes polynomial time!

There are important technical differences between Karp-reductions/transformations (R. Karp, 1972), and Turing-reductions (S. Cook, 1971), which we are ignoring here.

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Polynomial time reductions/transformations

NP-complete problems

A problem *X* is **NP-complete** if

- it is in *NP*
- for every problem $Y \in NP$: $Y \leq_p X$.

Theorem

Let *X* be an *NP*-complete problem. If we find a polynomial time algorithm for *X*, then $P = NP$.

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Polynomial time reductions/transformations

Theorem

Let X be an NP -complete problem. If we find a polynomial time algorithm for X , then $P = NP$.

Proof

Let A be a polytime algorithm for X . We have to show: $NP \subseteq P$. Let Y be any problem in NP . We will now give a polytime algorithm for Y . Let I be an instance of Y . Since X is NP -complete, there is an algorithm B which transforms any instance I of Y into an instance J of X in polynomial time, say in $p_B(|I|)$. In particular this implies $|J| \leq p_B(|I|)$. The algorithm A for X solves J in time $p_A(|J|) \leq p_A(p_B(|I|))$ (since all parameters are positive). Thus, we have an algorithm $C = A \circ B$ (B followed by A) for Y , which gives an answer to instance I in time at most $p_C(|I|) := p_B(|I|) + p_A(p_B(|I|))$, which, being a sum and composition of polynomials, is a polynomial in $|I|$.

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Is your problem NP -complete?

So if you have a computational problem, and you think it might be NP -complete, then

- Find it in the Garey-Johnson, or some other compendium of NP -complete/ NP -hard problems, or
- prove that it is NP -complete.
This is far beyond the scope of this course ...
You will learn how to do this in an advanced course on algorithms/complexity.

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Recap

- NP : problems which are polynomial-time checkable (for YES-instances, a certificate exists which can be verified in polynomial time)
- polynomial time reduction/transformation, $X \leq_p Y$, means: instances of X can be transformed to instances of Y in polynomial time
- NP -complete problems: problems in NP to which all problems in NP can be polytime reduced
- NP -hard problems: like NP -complete but not necessarily in NP
- An efficient (=polytime) algorithm for an NP -complete or NP -hard problem would imply: $P=NP$, which nobody believes is true
- Therefore, no efficient algorithm can exist for these problems (we all believe)

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Why do we believe that $P \neq NP$?

- Many, many important real-life problems are NP -complete or NP -hard.
- Finding an efficient algorithm for **just one of these** would prove $P = NP$.
- Much much work has gone into finding efficient algorithms for these.
- By some of the best mathematicians and computer scientists on earth.
- No one has been able to find an efficient algorithm for any one of these problems so far.

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Why do we believe that $P \neq NP$?

... by some of the best mathematicians and computer scientists on earth ...



"I can't find an efficient algorithm, but neither can all these famous people."

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What to do next?

If we find that our computational problem is NP -complete or NP -hard, then what can we do?

- despair/give up
- Run an **exhaustive search algorithm** – This is often possible for small instances, often combined with specific tricks.
- Verify that your instances are really general. Often, the general case is NP -complete, but many **special cases** are not!
E.g. the SBH-sequencing problem is **not** NP -complete: otherwise we could not have found a better formulation (Euler cycles in de Bruijn graphs) which is polynomially solvable!

(continued on next page)

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What to do next?

(continued from previous page)

- Devise **heuristics**: algorithms that work well in practice but without guaranteeing the quality of the solution.
- Polynomial time **approximation algorithms**: Algorithms that do not guarantee the optimal solution, but a solution which approximates the optimum. E.g. the Greedy Algorithm for SCS guarantees a solution which is at most 4 times longer than the optimum.
- and, and, and . . .

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Summary

- There are certain problems for which no efficient algorithms exist (very, very, very probably)
- These are called NP-complete (decision problems) or NP-hard (optimization problems)
- Many real-life problems, also in computational biology/bioinformatics, are NP-complete/NP-hard
- There are ways of dealing with this (see previous list)

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Summary

Merry Christmas!

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